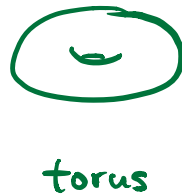
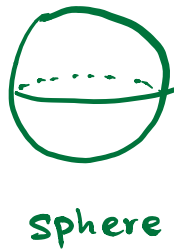
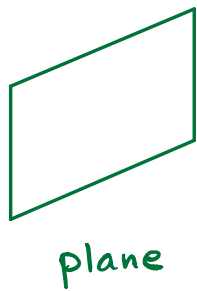
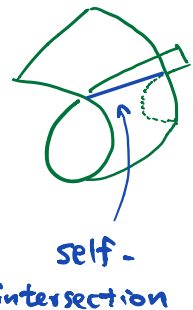
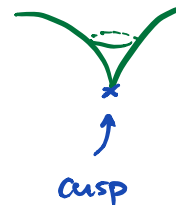
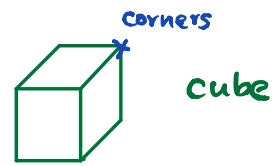


## § Surfaces in $\mathbb{R}^3$ (do Carmo § 2.2)

Q: Which one do we want to consider as "surfaces"?



YES



NO

Basic idea: A "surface" is an object that <sup>①</sup> locally  
<sup>②</sup> looks like a piece of  $\mathbb{R}^2$ .

Definition: A (regular) surface is a subset

$$S \subseteq \mathbb{R}^3$$

s.t.  $\forall p \in S, \exists$  nbd. of  $p$  (in  $S$ )  $V \subseteq S$

and a smooth map (called parametrization / chart)


$$\chi : \mathcal{U} \subseteq \mathbb{R}^2 \xrightarrow{\text{open}} V$$

s.t. (1)  $\chi : \mathcal{U} \rightarrow V$  is a homeomorphism.

\* (2) The differential  $d\chi|_q$  is 1-1  $\forall q \in \mathcal{U}$ .

Explanation on \* : More explicitly,

$$\mathbf{X}(u,v) = (x(u,v), y(u,v), z(u,v)) \quad , \quad \mathfrak{q} = (u,v) \in \mathcal{U}$$


  
smooth functions

The differential of  $\mathbf{X}$  at  $\mathfrak{q} \in \mathcal{U}$  is a linear map

$$d\mathbf{X}|_{\mathfrak{q}} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

which can be expressed in matrix form (w.r.t. std basis)

$$d\mathbf{X}|_{\mathfrak{q}} = \left( \begin{array}{cc} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{array} \right) \Big|_{\mathfrak{q}} =: \left( \begin{array}{c|c} \frac{\partial \mathbf{X}}{\partial u} & \frac{\partial \mathbf{X}}{\partial v} \\ \hline & \end{array} \right) \Big|_{\mathfrak{q}}$$

(\*)  $d\mathbf{X}|_{\mathfrak{q}}$  is 1-1  $\Leftrightarrow \frac{\partial \mathbf{X}}{\partial u}, \frac{\partial \mathbf{X}}{\partial v}$  are linearly independent.

Notation: We will write  $\mathbf{X}_u, \mathbf{X}_v$  to denote  $\frac{\partial \mathbf{X}}{\partial u}, \frac{\partial \mathbf{X}}{\partial v}$  respectively.

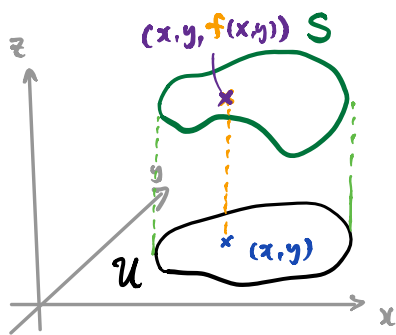
Remark: (\*) is equivalent to any one of the following:

- $\mathbf{X}_u \times \mathbf{X}_v \neq \vec{0}$  at  $\mathfrak{q}$
- $\text{rank}(d\mathbf{X}) = 2$  at  $\mathfrak{q}$

- $\exists 2 \times 2$  sub-matrix of  $d\mathbf{X}|_{\mathfrak{q}} = \left( \begin{array}{cc} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{array} \right) \Big|_{\mathfrak{q}}$  which is invertible.

## Example 1 : Graphical surfaces

Given a smooth function  $f: \mathcal{U} \subset \mathbb{R}^2 \rightarrow \mathbb{R}$



$$\begin{aligned} S &= \text{graph}(f) \\ &= \{ z = f(x, y) \mid (x, y) \in \mathcal{U} \} \end{aligned}$$

is a (regular) surface.

Why? Consider the smooth map

$$\begin{array}{ccc} \Sigma & : & \mathcal{U} \subset \mathbb{R}^2 \longrightarrow \mathcal{S} \subset \mathbb{R}^3 \\ \downarrow & & \downarrow \\ (u, v) & \longmapsto & (u, v, f(u, v)) \end{array}$$

Clearly,  $\Sigma: \mathcal{U} \rightarrow \mathcal{S}$  is a homeomorphism.

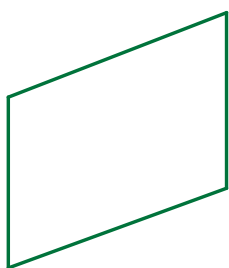
$$\left. \begin{aligned} \Sigma_u &:= \frac{\partial \Sigma}{\partial u} = \left( 1, 0, \frac{\partial f}{\partial u} \right) \\ \Sigma_v &:= \frac{\partial \Sigma}{\partial v} = \left( 0, 1, \frac{\partial f}{\partial v} \right) \end{aligned} \right\} \text{always linearly independent.}$$

Alternatively,

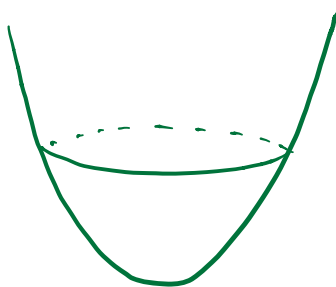
$$\Sigma_u \times \Sigma_v = \left( -\frac{\partial f}{\partial u}, -\frac{\partial f}{\partial v}, 1 \right) \neq \vec{0}$$

## Examples of graphical surfaces

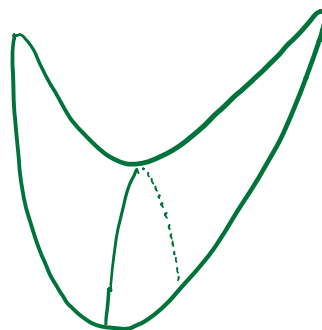
- $f(x,y) = ax + by + c \Rightarrow$  planes
- $f(x,y) = x^2 + y^2 \Rightarrow$  paraboloid
- $f(x,y) = x^2 - y^2 \Rightarrow$  hyperboloid



plane



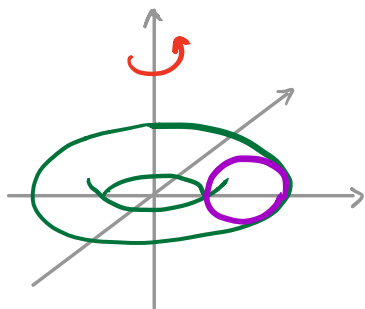
paraboloid



hyperboloid

Note: The entire surface can be covered by 1 chart.

## Example 2 : Torus of revolution



$$S = \{ (\sqrt{x^2 + y^2} - a)^2 + z^2 = r^2 \}$$

where  $a > r > 0$  are constants.

is a surface.

Define  $\Sigma : (0, 2\pi) \times (0, 2\pi) = U \rightarrow \mathbb{R}^3$  by

$$\Sigma(u, v) = \left( (a + r \cos u) \cos v, (a + r \cos u) \sin v, r \sin u \right)$$

Taking partial derivatives w.r.t.  $u$  and  $v$ ,

$$\Sigma_u = r \left( -\sin u \cos v, -\sin u \sin v, \cos u \right)$$

$$\Sigma_v = (a + r \cos u) \left( -\sin v, \cos v, 0 \right)$$

$$\Sigma_u \times \Sigma_v = r (a + r \cos u) \underbrace{\left( -\cos u \cos v, -\cos u \sin v, -\sin u \right)}_{\neq \vec{0}}$$

So  $\Sigma_u$  &  $\Sigma_v$  are linearly independent.

Exercise: How many parametrizations do we need to cover the whole torus?

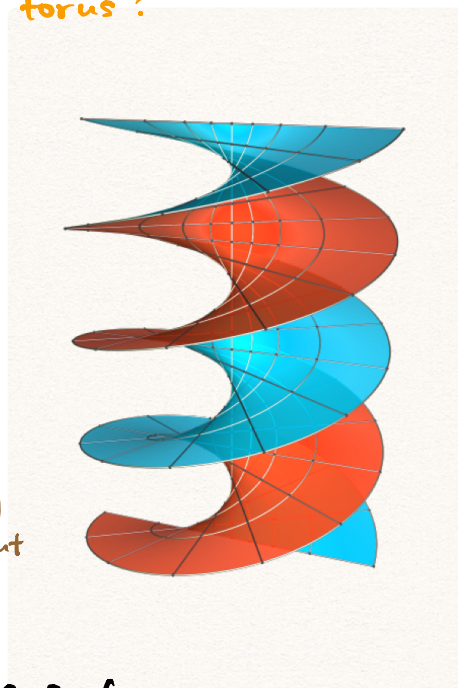
Example 3: Helicoid

Consider  $\Sigma: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  defined by

$$\Sigma(u, v) = (v \cos u, v \sin u, u)$$

$$\left. \begin{aligned} \Sigma_u &= (-v \sin u, v \cos u, 1) \\ \Sigma_v &= (\cos u, \sin u, 0) \end{aligned} \right\} \text{linearly independent}$$

Therefore, the image  $S := \Sigma(\mathbb{R}^2)$  is a surface.



### Example 4: Ruled Surfaces

Let  $\alpha: I \subseteq \mathbb{R} \rightarrow \mathbb{R}^3$  be a regular space curve,

$\beta: I \rightarrow \mathbb{R}^3$  be a smooth map s.t.  $\beta \neq \vec{0}$  everywhere

Define  $\Sigma: I \times \mathbb{R} \rightarrow \mathbb{R}^3$  be

$$\Sigma(u, v) = \alpha(u) + v\beta(u)$$

Q: Does  $\Sigma$  give a parametrization of a surface?

$$\Sigma_u = \alpha'(u) + v\beta'(u)$$

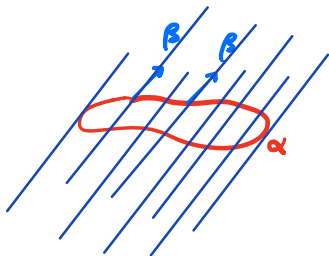
$$\Sigma_v = \beta(u)$$

$$\Rightarrow \Sigma_u \times \Sigma_v = \underbrace{\alpha'(u) \times \beta(u) + v(\beta'(u) \times \beta(u))}_{\text{Need: } \neq \vec{0}}$$

Examples include:

• generalized cylinder

( $\beta \equiv$  constant vector)



• cones

( $\beta = -\alpha$ )

